



Stabilization Of Programmed Motion

SJ Ball



Stabilization Of Programmed Motion:

Stabilization of Programmed Motion E Ya Smirnov,2000-09-20 This volume presents a particular aspect of control theory stabilization of programmed motion Methods of the construction and synthesis of stabilizing controls are introduced together with original results and useful examples The problem of optimal stabilization control synthesis is solved for linear systems of difference equations with quadratic quality criterion Dynamics And Robust Control Of Robot-environment Interaction

Miomir Vukobratovic,Dragoljub Surdilovic,Yury Ekalo,Dusko Katic,2009-03-06 This book covers the most attractive problem in robot control dealing with the direct interaction between a robot and a dynamic environment including the human robot physical interaction It provides comprehensive theoretical and experimental coverage of interaction control problems starting from the mathematical modeling of robots interacting with complex dynamic environments and proceeding to various concepts for interaction control design and implementation algorithms at different control layers Focusing on the learning principle it also shows the application of new and advanced learning algorithms for robotic contact tasks The ultimate aim is to strike a good balance between the necessary theoretical framework and practical aspects of interactive robots Partial Stability and Control

V.I. Vorotnikov,2012-12-06 Unlike the conventional research for the general theory of stability this mono graph deals with problems on stability and stabilization of dynamic systems with respect not to all but just to a given part of the variables characterizing these systems Such problems are often referred to as the problems of partial stability stabilization They naturally arise in applications either from the requirement of proper performance of a system or in assessing system capability In addition a lot of actual or desired phenomena can be formulated in terms of these problems and be analyzed with these problems taken as the basis The following multiaspect phenomena and problems can be indicated Lotka Volterra ecological principle of extinction focusing and acceleration of particles in electromagnetic fields drift of the gyroscope axis stabilization of a spacecraft by specially arranged relative motion of rotors connected to it Also very effective is the approach to the problem of stability stabilization with respect to all the variables based on preliminary analysis of partial stability stabilization A M Lyapunov the founder of the modern theory of stability was the first to formulate the problem of partial stability Later works by V V Rumyan tsev drew the attention of many mathematicians and mechanicians around the world to this problem which resulted in its being intensively worked out The method of Lyapunov functions became the key investigative method which turned out to be very effective in analyzing both theoretic and applied problems

Adaptive Mechanics Vladimir Ilyich Tertychnyĭ-Dauri,V.Y. Tertychny-Dauri,2002-02-28 Over the last thirty years an abundance of papers have been written on adaptive dynamic control systems Nevertheless now it may be predicted with confidence that the adaptive mechanics a new division new line of inquiry in one of the violently developing fields of cybernetic mechanics is emerging The birth process falls far short of being completed There appear new problems and methods of their solution in the framework of adaptive nonlinear dynamics Therefore the present work cannot be treated as a

certain polished brought to perfection school textbook More likely this is an attempt to show a number of well known scientific results in the parametric synthesis of nonlinear systems this strictly speaking accounts for the availability of many reviews as well as to bring to notice author s developments on this question undoubtedly modern and topical The nonlinear and practically Lagrangian systems cover a wide class of classical objects in theoretical mechanics and primarily solid body robotic gyroscopic rocket cosmic and other systems And what is rather important they have a direct trend to practical application To indicate this discussion I should like to notice that it does not touch upon the questions concerned with the linear and stochastic control objects Investigated are only nonlinear deterministic systems being in the conditions when some system parameters are either unknown or beyond the reach of measurement or they execute an unknown limited and fairly smooth drift in time

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