



The Three Robots

Borzoo Bonakdarpour, Franck Petit



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Algorithms and Computation Seok-Hee Hong, Hiroshi Nagamochi, Takuro Fukunaga, 2008-12 This book constitutes the refereed proceedings of the 19th International Symposium on Algorithms and Computation ISAAC 2008 held in Gold Coast Australia in December 2008 The 78 revised full papers together with 3 invited talks presented were carefully reviewed and selected from 229 submissions for inclusion in the book The papers are organized in topical sections on approximation algorithms online algorithms data structure and algorithms game theory graph algorithms fixed parameter tractability distributed algorithms database approximation algorithms computational biology computational geometry complexity networks optimization as well as routing

Stabilization, Safety, and Security of Distributed Systems Borzoo Bonakdarpour, Franck Petit, 2016-11-01 This book constitutes the refereed proceedings of the 18th International Symposium on Stabilization Safety and Security of Distributed Systems SSS 2016 held in Lyon France in November 2016 This year the Program Committee was organized into three groups reflecting the major trends related to self systems a Self and Autonomic Computing b Foundations and c Networks Multi Agent Systems and Mobility

Structured Object-Oriented Formal Language and Method Shaoying Liu, Zhenhua Duan, Cong Tian, Fumiko Nagoya, 2017-04-20 This book constitutes revised selected papers from the 6th International Workshop on Structures Object Oriented Formal Language and Method SOFL MSVL 2016 held in Tokyo Japan in November 2016 The 13 papers presented in this volume were carefully reviewed and selected from 26 submissions They are organized in topical sections named modeling and specification animation and prototyping verification and validation and model checking

Human Interaction & Emerging Technologies (IHIET-AI 2024) Tareq Ahram, Redha Taiar, 2024-04-25 Proceedings of the 11th International Conference on Human Interaction and Emerging Technologies Artificial Intelligence Future Applications IHIET AI 2024 which was held April 25 27 2024 at the Centre Hospitalier Universitaire Vaudois CHUV Lausanne Switzerland

Intelligent Robotics and Applications YongAn Huang, Hao Wu, Honghai Liu, Zhouping Yin, 2017-08-04 The three volume set LNAI 10462 LNAI 10463 and LNAI 10464 constitutes the refereed proceedings of the 10th International Conference on Intelligent Robotics and Applications ICIRA 2017 held in Wuhan China in August 2017 The 235 papers presented in the three volumes were carefully reviewed and selected from 310 submissions The papers in this third volume of the set are organized in topical sections on sensors and actuators mobile robotics and path planning virtual reality and artificial intelligence aerial and space robotics mechatronics and intelligent manufacturing

Distributed Computing by Mobile Entities Paola Flocchini, Giuseppe Prencipe, Nicola Santoro, 2019-01-12 Distributed Computing by Mobile Entities is concerned with the study of the computational and complexity issues arising in systems of decentralized computational entities operating in a spatial universe Encompassing and modeling a large variety of application environments and systems from robotic swarms to networks of mobile sensors from software mobile agents in communication networks to crawlers and viruses on the web the theoretical research in this

area intersects distributed computing with the fields of computational geometry especially for continuous spaces control theory graph theory and combinatorics especially for discrete spaces The research focus is on determining what tasks can be performed by the entities under what conditions and at what cost In particular the central question is to determine what minimal hypotheses allow a given problem to be solved This book is based on the lectures and tutorial presented at the research meeting on Moving and Computing mac held at La Maddalena Island in June 2017 Greatly expanded revised and updated each of the lectures forms an individual Chapter Together they provide a map of the current knowledge about the boundaries of distributed computing by mobile entities

Stabilization, Safety, and Security of Distributed Systems Paul Spirakis,Philippas Tsigas,2017-10-20 This book constitutes the refereed proceedings of the 19th International Symposium on Stabilization Safety and Security of Distributed Systems SSS 2017 held in Boston MA USA in November 2017 The 29 revised full papers presented together with 8 revised short papers were carefully reviewed and selected from 68 initial submissions This year the Symposium was organized into three tracks reflecting major trends related to self systems Stabilizing Systems Theory and Practice Distributed Computing and Communication Networks and Computer Security and Information Privacy

Structural Information and Communication Complexity Shantanu Das,Sebastien Tixeuil,2017-12-30 This book constitutes the thoroughly refereed proceedings of the 24th International Colloquium on Structural Information and Communication Complexity SIROCCO 2017 held in Porquerolles France in June 2017 The 21 full papers presented were carefully reviewed and selected from 41 submissions They are devoted to the study of the interplay between structural knowledge communications and computing in decentralized systems of multiple communicating entities They are organized around the following topics wireless networks identifiers and labeling mobile agents probabilistic algorithms computational complexity dynamic networks

Proceedings of the International Symposium and Exposition on Robots ,1982

Multirobot Systems Rajiv Mehrotra,Murali R. Varanasi,1990

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Automatic Control and Mechatronic Engineering II Hirotaka Tanabe,2013-09-03 Selected peer reviewed papers from the 2nd International Conference on Automatic Control and Mechatronic Engineering ICACME 2013 June 21 22 2013 Bangkok Thailand

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Robotics and the Factory of the Future ,1983

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