



Symbolic Software For Interactive Descriptions Of Dynamic Systems

Arthur James Wells



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Symbolic Software for Interactive Descriptions of Dynamic Systems G. Paul Wilhelmij,1991 **Symbolic Software for Interactive Descriptions of Dynamic Systems** G. Paul Wilhelmij,1991 By G Paul Wilhelmij *Completeness, Confluence, and Related Properties of Clause Graph Resolution* Norbert Eisinger,1991 **Meta-level Inference Systems** Frank Van Harmelen,1991 **Technical Report** Massachusetts Institute of Technology. Hydrodynamics Laboratory,1993 **A Bibliography for the Development of an Intelligent Mathematical Programming System** Harvey J. Greenberg,1995 Artificial Intelligence and Operations Research in Business and Management Daniel Edmund O'Leary,1996 *Interactive Task Learning* Kevin A. Gluck,John E. Laird,2019-08-16 Experts from a range of disciplines explore how humans and artificial agents can quickly learn completely new tasks through natural interactions with each other Humans are not limited to a fixed set of innate or preprogrammed tasks We learn quickly through language and other forms of natural interaction and we improve our performance and teach others what we have learned Understanding the mechanisms that underlie the acquisition of new tasks through natural interaction is an ongoing challenge Advances in artificial intelligence cognitive science and robotics are leading us to future systems with human like capabilities A huge gap exists however between the highly specialized niche capabilities of current machine learning systems and the generality flexibility and in situ robustness of human instruction and learning Drawing on expertise from multiple disciplines this Str ngmann Forum Report explores how humans and artificial agents can quickly learn completely new tasks through natural interactions with each other The contributors consider functional knowledge requirements the ontology of interactive task learning and the representation of task knowledge at multiple levels of abstraction They explore natural forms of interactions among humans as well as the use of interaction to teach robots and software agents new tasks in complex dynamic environments They discuss research challenges and opportunities including ethical considerations and make proposals to further understanding of interactive task learning and create new capabilities in assistive robotics healthcare education training and gaming Contributors Tony Belpaeme Katrien Beuls Maya Cakmak Joyce Y Chai Franklin Chang Ropafadzo Denga Marc Destefano Mark d Inverno Kenneth D Forbus Simon Garrod Kevin A Gluck Wayne D Gray James Kirk Kenneth R Koedinger Parisa Kordjamshidi John E Laird Christian Lebiere Stephen C Levinson Elena Lieven John K Lindstedt Aaron Mininger Tom Mitchell Shiwali Mohan Ana Paiva Katerina Pastra Peter Pirolli Roussell Rahman Charles Rich Katharina J Rohlfing Paul S Rosenbloom Nele Russwinkel Dario D Salvucci Matthew Donald D Sangster Matthias Scheutz Julie A Shah Candace L Sidner Catherine Sibert Michael Spranger Luc Steels Suzanne Stevenson Terrence C Stewart Arthur Still Andrea Stocco Niels Taatgen Andrea L Thomaz J Gregory Trafton Han L J van der Maas Paul Van Eecke Kurt VanLehn Anna Lisa Vollmer Janet Wiles Robert E Wray III Matthew Yee King **Quality and Communicability for Interactive Hypermedia Systems: Concepts and Practices for Design** Cipolla-Ficarra, Francisco Vicente,2010-02-28

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