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Hendrik Nijmeijer, Thor I. Fossen



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Stabilization of Nonlinear Uncertain Systems Miroslav Krstić, 1998 *Adaptive Control of Dynamic Systems with Uncertainty and Quantization* Jing Zhou, Lantao Xing, Changyun Wen, 2021-12-14 This book presents a series of innovative technologies and research results on adaptive control of dynamic systems with quantization uncertainty and nonlinearity including the theoretical success and practical development such as the approaches for stability analysis the compensation of quantization the treatment of subsystem interactions and the improvement of system tracking and transient performance Novel solutions by adopting backstepping design tools to a number of hotspots and challenging problems in the area of adaptive control are provided In the first three chapters the general design procedures and stability analysis of backstepping controllers and the basic descriptions and properties of quantizers are introduced as preliminary knowledge for this book In the remainder of this book adaptive control schemes are introduced to compensate for the effects of input quantization state quantization both input and state output quantization for uncertain nonlinear systems and are applied to helicopter systems and DC Microgrid Discussion remarks are provided in each chapter highlighting new approaches and contributions to emphasize the novelty of the presented design and analysis methods Simulation results are also given in each chapter to show the effectiveness of these methods This book is helpful to learn and understand the fundamental backstepping schemes for state feedback control and output feedback control It can be used as a reference book or a textbook on adaptive quantized control for students with some background in feedback control systems Researchers graduate students and engineers in the fields of control information and communication electrical engineering mechanical engineering computer science and others will benefit from this book *Analysis and Decision Making in Uncertain Systems* Zdzislaw Bubnicki, 2004-01-09 A unified and systematic description of analysis and decision problems within a wide class of uncertain systems described by traditional mathematical methods and by relational knowledge representations Prof Bubnicki takes a unique approach to stability and stabilization of uncertain systems **Nonlinear Control of Dynamic Networks** Tengfei Liu, Zhong-Ping Jiang, David J. Hill, 2018-09-03 Significant progress has been made on nonlinear control systems in the past two decades However many of the existing nonlinear control methods cannot be readily used to cope with communication and networking issues without nontrivial modifications For example small quantization errors may cause the performance of a well designed nonlinear control system to deteriorate Motivated by the need for new tools to solve complex problems resulting from smart power grids biological processes distributed computing networks transportation networks robotic systems and other cutting edge control applications *Nonlinear Control of Dynamic Networks* tackles newly arising theoretical and real world challenges for stability analysis and control design including nonlinearity dimensionality uncertainty and information constraints as well as behaviors stemming from quantization data sampling and impulses Delivering a systematic review of the nonlinear small gain theorems the text Supplies novel cyclic small gain theorems for large scale nonlinear

dynamic networks Offers a cyclic small gain framework for nonlinear control with static or dynamic quantization Contains a combination of cyclic small gain and set valued map designs for robust control of nonlinear uncertain systems subject to sensor noise Presents a cyclic small gain result in directed graphs and distributed control of nonlinear multi agent systems with fixed or dynamically changing topology Based on the authors recent research Nonlinear Control of Dynamic Networks provides a unified framework for robust quantized and distributed control under information constraints Suggesting avenues for further exploration the book encourages readers to take into consideration more communication and networking issues in control designs to better handle the arising challenges ,1997 **SIAM Journal on Control and Optimization** Society for Industrial and Applied Mathematics,2005 **Deterministic Control of Nonlinear Uncertain Systems** Sandeep Pandey,1992 Control Applications of Optimization 2000 (CAO 2000) Valeriï Nikolaevich Zakharov,2000 Robust Control Via Variable Structure and Lyapunov Techniques Franco Garofalo,Luigi Glielmo,1996 A large part of today s fervour on robust control research is focused on those techniques which utilise the Variable Structure Control Method and Lyapunov s Second Method and which constitute the backbone of the so called deterministic control of uncertain systems The chapters of this book cover a large spectrum of the recent research and introduce the most innovative ideas in the field Contained within the volume the reader will find a survey of control Lyapunov functions new structures of sliding mode controllers with discussion on higher order sliding modes new techniques for the design of direct and indirect adaptive controllers an introduction to the geometric theory of flat systems controllers for plants with component wise bounded inputs robust design via linear matrix inequalities and polytopic covering and some issues on the dissipativity and absolute stability of nonli near systems **Proceedings of the ... American Control Conference** ,1998 **New Directions in Nonlinear Observer Design** Hendrik Nijmeijer,Thor I. Fossen,1999-05-21 The past decade has witnessed an increasing interest in observers for nonlinear systems This subject is relevant in different contexts such as synchronization of complex dynamical systems fault detection and isolation and output feedback control This book contains the contributions that are to be presented at the workshop New Directions in Nonlinear Observer Design to be held from June 24 26 1999 in Geiranger Fjord Norway The workshop has been organised by Olav Egeland Thor I Fossen and Henk Nijmeijer it will include participants from Africa Asia Europe and USA and it will focus on recent developments in the above mentioned areas The contributions form a good review of present achievements and challenges in nonlinear observer design The workshop is supported by the Strategic University Program on Marine Cybernetics at the Norwegian University of Science and Technology and ABB **Robust Control Design Using H-∞ Methods** Ian R. Petersen,Valery A. Ugrinovskii,Andrey V. Savkin,2012-12-06 This is a unified collection of important recent results for the design of robust controllers for uncertain systems primarily based on H8 control theory or its stochastic counterpart risk sensitive control theory Two practical applications are used to illustrate the methods throughout **Stabilization and Regulation of Nonlinear Systems** Zhiyong Chen,Jie Huang,2014-08-30 The core of this

textbook is a systematic and self contained treatment of the nonlinear stabilization and output regulation problems Its coverage embraces both fundamental concepts and advanced research outcomes and includes many numerical and practical examples Several classes of important uncertain nonlinear systems are discussed The state of the art solution presented uses robust and adaptive control design ideas in an integrated approach which demonstrates connections between global stabilization and global output regulation allowing both to be treated as stabilization problems Stabilization and Regulation of Nonlinear Systems takes advantage of rich new results to give students up to date instruction in the central design problems of nonlinear control problems which are a driving force behind the furtherance of modern control theory and its application The diversity of systems in which stabilization and output regulation become significant concerns in the mathematical formulation of practical control solutions whether in disturbance rejection in flying vehicles or synchronization of Lorenz systems with harmonic systems makes the text relevant to readers from a wide variety of backgrounds Many exercises are provided to facilitate study and solutions are freely available to instructors via a download from springerextras.com Striking a balance between rigorous mathematical treatment and engineering practicality Stabilization and Regulation of Nonlinear Systems is an ideal text for graduate students from many engineering and applied mathematical disciplines seeking a contemporary course in nonlinear control Practitioners and academic theorists will also find this book a useful reference on recent thinking in this field *Proceedings of the ASME Dynamic Systems and Control Division* ,1998

Proceedings of the 33rd IEEE Conference on Decision and Control ,1994 **Proceedings of the 26th IEEE Conference on Decision and Control** ,1987 **Journal of Dynamic Systems, Measurement, and Control** ,2007
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