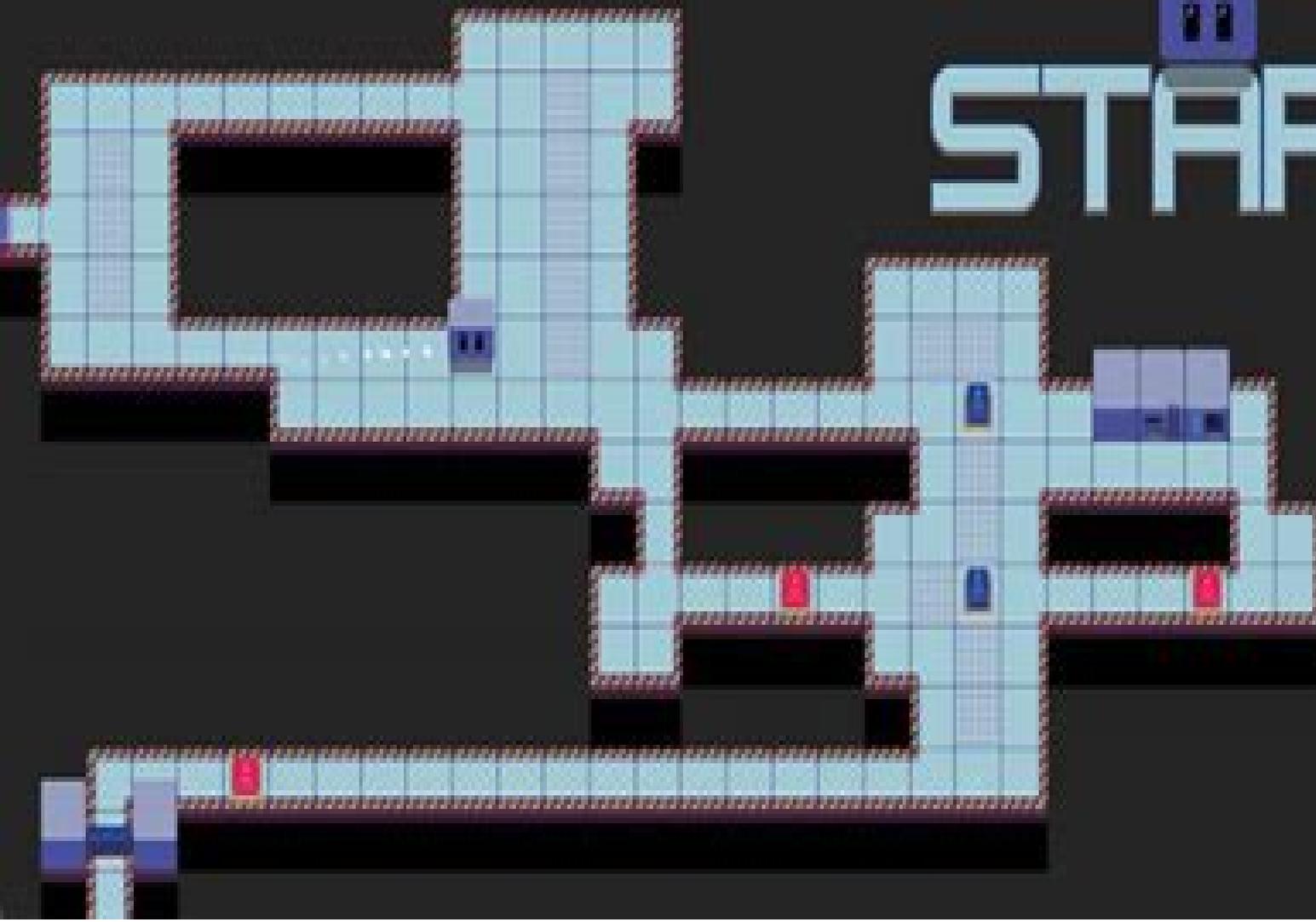


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Advances in the Integration of Brain-Machine Interfaces and Robotic Devices Luca Tonin, Emanuele Menegatti, Damien Coyle, 2021-04-07 Modeling, Simulation, And Control Of Flexible Manufacturing Systems: A Petri Net Approach Kurapati Venkatesh, Mengchu Zhou, 1999-01-29 One critical barrier leading to successful implementation of flexible manufacturing and related automated systems is the ever increasing complexity of their modeling analysis simulation and control Research and development over the last three decades has provided new theory and graphical tools based on Petri nets and related concepts for the design of such systems The purpose of this book is to introduce a set of Petri net based tools and methods to address a variety of problems associated with the design and implementation of flexible manufacturing systems FMSs with several implementation examples There are three ways this book will directly benefit readers First the book will allow engineers and managers who are responsible for the design and implementation of modern manufacturing systems to evaluate Petri nets for applications in their work Second it will provide sufficient breadth and depth to allow development of Petri net based industrial applications Third it will allow the basic Petri net material to be taught to industrial practitioners students and academic researchers much more efficiently This will foster further research and applications of Petri nets in aiding the successful implementation of advanced manufacturing systems Build Your Own Teams of Robots with LEGO® Mindstorms® NXT and Bluetooth® Cameron Hughes, Tracey Hughes, Trevor Watkins, Bob Kramer, 2013-02-22 CREATE YOUR OWN SYNCHRONIZED ROBOT ARMY PLAN DESIGN ASSEMBLE AND PROGRAM ROBOT SQUADS THAT COMMUNICATE and cooperate with each other to accomplish together what they can't do individually Build Your Own Teams of Robots with LEGO MINDSTORMS NXT and Bluetooth shows you how to construct a team capability matrix TCM and use the Bluetooth Robotic Oriented Network BRON so your robot teams can share sensors actuators end effectors motor power and programs Find out how the Bluetooth communications protocol works and how to program Bluetooth in NXT G NXC LabVIEW and Java Learn how to send and receive Bluetooth messages data and commands among robots between a robot and a computer and between an Android smart phone and a robot Through teamwork your robots will be able to accomplish amazing feats THE STEP BY STEP ROBOT TEAM PROJECTS IN THE BOOK INCLUDE Crime Scene Investigation Robot Team Robot Convoy Rubik's Cube Solver LEARN HOW TO Coordinate multiple robots to work together as a team to perform tasks Combine two or more microcontrollers to make a single multicontroller multi agent robot Take advantage of sensor and actuator capabilities in a team environment Establish goals and teamwork strategies for your robots Control your robot teams with NXT G Bluetooth bricks and LabVIEW for NXT Bluetooth VI Activate your team using a smart phone Give your team of robots Java power with leJOS Use Java on the Linux and Darwin operating systems Watch video demonstrations of the projects and download code and examples in multiple languages NXT G Java LabVIEW and NXC from the book's companion website at www.robotteams.org Downloads are also available at mhprofessional.com/robotteams **Robotics and Manufacturing**

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